Automatic Extraction of Features and Generation of Feature Models from Java Programs

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Abstract. Feature modelling is a key technique for identifying common and variable features in software (software component families). The result of feature modelling is a feature model: a concise specification of product features and their relationships. Feature models have been proven to be useful for software variability modelling and management. However, there is a wide gap between feature models and program source code. Here we focus on reverse engineering of source code to feature models. We present a framework for the automated derivation of feature models from the existing software artefacts (components, libraries, etc.), which includes a formal description of a feature model, a program-feature relation meta-model, and a method for feature model generation based on feature dependency extraction and clustering. Feature models are generated in Feature Description Language (FDL) and as Prolog rules.

Keywords: program analysis, reverse engineering, feature modelling, model generation.

1. Introduction

Programming is the process of turning features, concepts, patterns, models and designs into source code. The process is performed either 1) manually, by a programmer writing source code, 2) semi-automatically, e.g., by a code generator generating code templates from a high-level model and then the programmer filling in the missing details, or 3) automatically, e.g., by a compiler compiling source code into executables.

The process of discovering higher-level concepts (features, patterns, models, etc.) in source code is called de-programming [1]. Extracting program dependency graphs [2], causal dependencies [3], facts [4], detecting code clones [5], finding design patterns [6] and architectural models [7], architecture recovery [8], reengineering [9], reconstruction [10], ontology learning [11], vertical program transformations [12] are examples of such activity. More broadly, such activity can be understood as a part of reverse engineering, i.e., “the process of analyzing a subject system to create representations of the system at a higher level of abstraction.” [13].

In this paper we focus on reverse engineering of software to feature models. The activity also has been defined as ‘feature model mining’ [14] and ‘product line reengineering’ [15]. A feature model is a representation of concepts in a domain in terms of features, their variabilities and dependencies [16]. Feature models can be represented visually using Feature Diagrams [17] as well as formally [18] or textually [37]. Feature modelling is a key technique for identifying common and variable features in a software family and formalizing such analysis in the form of a feature model.

Currently, feature models are constructed by a domain analyst manually using the top-down approach from user requirements for a future system, or from feature descriptions of existing software systems. However, another approach (‘bottom-up’) can be envisioned, when features are identified and feature models are constructed from the existing software artefacts. Identifying the parts of the source code that correspond to a specific functionality is a prerequisite to program comprehension and is one of the most common activities undertaken by developers. This process is called the concept (or feature) location [19]. Features are special concepts that are associated with the user-visible functionality of the system. The shared goal of these techniques is to identify computational units (e.g., methods, functions, classes, etc.) that specifically implement a concept of interest from the problem or solution domain of the software. Concept
location is an important activity in software evolution and software maintenance.

The problem of feature extraction is known under several names in computer science research: feature mining [14], fact extraction [4], model extraction [20], concept analysis [21], feature location [22, 23], concept location [24], dependency finding [3], concept assignment [25], semantic clustering and topic mining [26], pattern discovery [27, 28], etc.

Biggerstaff et al. [25] define a concept assignment problem as the problem of “discovering human-oriented concepts and assigning them to their realizations”. The process is difficult to be automated, because the concept (feature) and program source code are not at the same level of abstraction. To perform concept assignment, an expert the specific domain and a reasoning mechanism are needed. Usually, some form of human input is needed to enrich source code with additional information in order to help tools to extract and arrange higher-level concepts. For example, Basten and Klint [4] perform fact extraction from Java programs by attaching fact extraction annotations to a single syntax rule and extracting local facts from parse tree fragments.

The feature-feature and feature-code relationships can be modelled using various mathematical structures. For example, Sangal et al. [2] use a dependency structure matrix. Snelling and Tip [21] use Formal Concept Analysis (FCA) to analyze legacy code aiming to reconstruct the overall system structure by determining which variables (columns) were accessed by which modules (rows). Pfaltz [3] describes a methodology based on the formal concept analysis that uncovers possible causal dependencies in execution trace streams. Structures used for information retrieval include call-graph information to automatically assign features to respective elements in source code [29] and complex networks of software dependence [30].

In the context of feature modelling and product line engineering, She et al. [14] use association rule mining to retrieve the necessary propositional formulas to find feature groups, mandatory features, implies/exclude edges, and to construct a probabilistic feature model from a set of individual configurations, which consist of a list of features defined as system properties that a stakeholder is interested in. Yang et al. [31] recover domain feature models using FCA, concept pruning/merging, structure reconstruction and variability analysis. Poshyvanyk and Marcus [32] combine an information retrieval based technique with scenario-based probabilistic ranking of the execution traces to improve the precision of feature location. Salah and Mancoridis [33] combine both static (dependencies) and dynamic (execution traces) information to identify features in Java programs and use FCA to relate features together.

Summarising, though a number of methods exist to locate and retrieve higher-level concepts from source code such as features, none of them are actually automatic and allow building feature models from the source code itself. The novelty of this paper is a proposed method for the automatic derivation of feature models from Java source code.

2. Framework for automatic derivation of feature models

To define a framework, first, we must define a model of domain, specify basic types of program dependencies, construct program-feature meta-model, and provide a detailed description of the methodology.

2.1. Domain model

Our domain of research is programs, which are understood in terms of structural programming. A program consists of components. Each component has variables to store component’s state, computations performed on variable values and references to other components. Data are passed between components via variables. In an object-oriented language such as Java, we have a program consisting of multiple classes. Each class can have attributes (fields), methods, and references to other classes. Each method, in turn, can have its own local variables, references to other classes and methods. For simplicity reasons, we consider both a class and a method as a component, though Java does not allow stand-alone methods (functions). Also we do not differentiate between classes per se, abstract classes and interfaces.

2.2. Program dependencies

We follow a detailed taxonomy of relations in Java programs, which is presented by [20]. All relation types represent a dependency, with the dependency direction being the direction of the relation; in this way, the extracted relations form a dependency graph. In general, dependencies can be direct, transitive, or cyclic [34]. A direct dependency exists between two items, dependent and dependee. A transitive dependency occurs when two items are linked via one or more intermediary nodes. A cyclic dependency is a relation between two or more modules which either directly or indirectly depend on each other to function. Relations and dependencies in Java program entities are summarized in Fig. 1.

![Figure 1. Relationship of program entities](image-url)
2.3. Feature model

The feature model consists of a hierarchy of features, a set of selection functions (AND, OR, CASE) to select a feature, and a set of constraints expressed by propositional formulas, which must be satisfied in a legal configuration. Formally, a feature is a \textit{coloured vertex} \( x^c_i \) (\( x^c_i \in X^c \)) of the total \textit{coloured feature graph} \( G(X^c, V^c) \), where \( X^c \) is a set of vertices, and \( V^c \) is a set of edges. A relationship between features is a sub-graph \( G_p(X^c_p, U^c_p) \), where \( X^c_p = x^c_p \cup X^c_d \) is a set of vertices, \( x^c_p \in X^c \) is a parent vertex, \( X^c_d \subseteq X^c \) is a set of vertices (grouped features) that are descendants (children) of \( x^c_p \), \( U^c_p \subseteq U^c \subseteq V^c \) is a set of edges that connects \( x^c_p \) to each member of \( X^c_d \).

Feature diagram is a bi-coloured directed graph \( G(X^c, V^c) \) formed by the composition of the bi-coloured featured tree \( T(X^c, U^c) \) and a set of edges \( B \) representing constraints between vertices \( X^c_B \subseteq X^c \), where \( U^c \) is a set of directed edges representing parent-child relationships of a pair of vertices; \( V^c = U^c \cup B \).

The process of feature selection for product implementation can be described as colouring of a feature diagram. There are two colours to specify the current state of a feature in a feature graph: white – unselected, black – selected. There are two colours of edges defined in terms of modal logic: white and black. Based on the feature diagram colouring rules, there are three types of features: mandatory, optional and alternative. A white-coloured edge means that a descendant vertex \( x^c_d \), \( x^c_d \in X^c_d \), may be \textit{possibly} selected if its parent vertex \( x^c_p \) is selected, i.e. \( x^c_p \rightarrow \neg \neg x^c_d \). A black-coloured edge means that a descendant vertex \( x^c_d \) must be \textit{necessarily} be selected if its parent vertex \( x^c_p \) is selected, i.e. \( x^c_p \rightarrow x^c_d \).

A descendant feature that is related with its parent feature by a black-coloured edge is called a \textit{mandatory} feature. Optional feature is a member of feature group \( X^c_p \subseteq X^c \) that is related with its parent feature \( x^c_p \) by a white-coloured edge. Any optional features may be selected independently from other optional features in its feature group, i.e., \( x^c_p \rightarrow \neg x^c_d \), \( \forall x^c_d \in X^c_d \).

Alternative feature is a member of feature group \( X^c_d \subseteq X^c \) that is related with its parent feature \( x^c_p \) by a white-coloured edge. \textit{Exactly one} alternative feature must be selected from its feature group, i.e., \( x^c_p \rightarrow x^c_d \), \( x^c_d \in X^c_d \) and \( x^c_p \rightarrow \neg \neg x^c_d \), \( \forall x^c_d \in X^c_d, j \neq i \).

A feature that has no parents is called the \textit{root} feature. There is only one root feature in the graph \( G \). A feature that is a parent of either an optional or an alternative feature group is called a \textit{variant point}. A feature that has no descendants is a \textit{variant}.

Constraint is a \textit{predicate} of a prescribed type between two variants \( x^c_i \) and \( x^c_j \) in \( G \), i.e., \( b_i : (x^c_i, x^c_j) \rightarrow \{\text{true, false}\} \), \( b_i \in B, x^c_i, x^c_j \in X^c \). The predicate evaluates to \textit{true}, if the constraint exists, otherwise the predicate evaluates to \textit{false}. The requires constraint indicates that the selection of one variant requires that some another variant must be selected, i.e., \( \{\text{color}(x^c_i) \rightarrow \text{black} \rightarrow \text{color}(x^c_j) \rightarrow \text{black}\} \), if \( b_{\text{req}}(x^c_i, x^c_j) \rightarrow \text{true} \). The excludes constraint indicates that the selection of one variant excludes the selection of \textit{some} another variant, i.e., \( \{\text{color}(x^c_i) \rightarrow \text{black} \rightarrow \text{color}(x^c_j) \rightarrow \text{white}\} \), if \( b_{\text{exc}}(x^c_i, x^c_j) \rightarrow \text{true} \).

Feature path \( P \) is a sub-graph of \( G \) that contains only black-coloured vertices, i.e. features selected by a stakeholder. Feature path is a \textit{complete} feature path, if it contains no variant points. Complete feature path is constructed from a feature graph \( G \), when a stakeholder makes all available selections of features.

Configuration \( c \) is a \textit{multi-set} of all features in the feature path \( P \). Configuration \( c \) is a \textit{valid} configuration, if 1) it is not empty, 2) it contains no variant points, 3) the multiplicities of elements belonging to the multi-set are equal to 1, i.e., it contains only unique features, 4) all features in the multi-set satisfy a set of constraints \( B \) in graph \( G \). The configuration set \( C \) is a set of all valid configurations of feature graph \( G \).

2.4. Program-Feature Meta-Model

Combining the concepts described in subsection 2.2 and introduced in subsection 2.3, we propose a program-feature relation meta-model (see Fig. 2). The concepts of this meta-model are explained as follows.

An atomic feature is a basic unit of computation in a program such as variable or function (method). A composite feature is a composition of atomic features. A software component (class) is a particular (meaningful) composition of related atomic and/or composite features. A dependency is a relationship between atomic or composite features. Feature \( A \) depends on feature \( B \) if feature \( A \) references feature \( B \). For example, method \( A() \) uses the value of variable \( B \) or calls a method \( B() \).
2.5. Methodology

Our methodology of feature model extraction from Java programs is as follows:

1) **Compile Java source code using a standard Java compiler**

2) **Extract feature dependencies from Java class files**

Feature dependencies are modelled using a dependency graph \( G \). The dependency graph \( G \) is a directed graph that is described formally as follows:

\[
G = (F, D)
\]

where \( F \) is a set of vertices representing features, and \( D \) is a set of dependencies. Feature dependencies are extracted by parsing a Java class file. A class file is a component of a Java executable corresponding to a single Java class. It contains tables describing the structure of the class and virtual machine byte code for the class methods. Parsing Java class files is a reliable and straightforward way to find dependencies among Java classes [35].

3) **Construct a feature distance matrix**

For further manipulations, the dependency graph \( G \) is expressed as the adjacency matrix \( A \) of size \( |F| \), where \( a_{ij} = 1 \), if feature \( i \) depends on feature \( j \). The adjacency matrix allows to describe only direct dependencies. To describe indirect dependencies, the matrix \( A \) is converted to the distance (dissimilarity) matrix \( M \) of size \( |F| \), where \( m_{ij} \) is equal to the shortest path distance between feature \( i \) and feature \( j \). Both matrices \( A \) and \( M \) are asymmetric, because the dependency graph \( G \) is directed. The matrix \( A \) is converted to the matrix \( M \) using the Floyd’s all pairs shortest path algorithm.

4) **Cluster features based on their dependency in a feature tree**

Given a dependency graph \( G = (V, E) \), a cluster is defined as a sub-graph \( G' = (V', E') \), whose nodes are tightly connected, i.e. cohesive. A cluster tree is a directed acyclic graph \( T = (C, R) \), where \( C \) is a set of clusters and \( R \) is a set of relations between clusters. Each cluster corresponds to a subset of atomic and/or composite features that are more related to each other than other features. The root of the tree \( T \) is a single cluster that contains all features from \( F \). The nodes of the tree correspond to the composite features. The leaves of the cluster tree \( T \) correspond to the atomic features.

To derive composite features, we cluster atomic features based on their dependency information. Selection of number of clusters is a separate problem, because the size of the feature model directly depends upon the number of discovered clusters. Too fine-grained clustering leads to overly detailed specification of features in a feature model, thus making it incomprehensible and not reusable. To set a number of clusters, we follow a simple rule of thumb

\[
k = \sqrt{\frac{n}{2}}
\]

where \( n \) is the number of atomic features, and \( k \) is the number of clusters (composite features). For clustering, we define class methods as features; and instantiations of other classes, calls to other methods, and use of class variables as attributes.

In practice, any clustering algorithm, which can produce hierarchical dendrogram as a result (e.g., fast greedy algorithm which maximizes modularity measure, Girvan-Newman edge betweenness algorithm and walktrap community detection are some of the alternatives), can be used at this stage, the ad hoc recommendation is to use the incremental single-scan hierarchical clustering algorithms capable of
building balanced trees such as Cobweb [36] from the WEKA package.

5) Convert a feature tree into a feature model

Finally, the cluster tree \( T \) is converted to a feature model \( F_M \), where all nodes from a set of clusters \( C \) are mapped to feature nodes, relation between clusters is described by an optional relationship, and constraints are added using information from the adjacency matrix \( A \) (\( f_i \ <\text{requires}> f_j \) if \( a_{ij} = 1 \)).

The problem is how to set feature relationships, i.e., which features are to be marked as mandatory, and which optional (alternative). The analyzed program represents only one possible combination of program's features, whereas a feature model represents a set of possible feature combinations. We tackle this problem as follows. We denote root node relations as mandatory and all other relations as alternative. We however claim that additional constrains between features should be discovered at a later stage, i.e., during feature modelling.

6) Generate description of feature model in FDL/Prolog

The results are saved using a Feature Description Language (FDL) [37] format for further representation and usage in the feature modelling environment FD2, which is currently under development, and in Prolog as a set of rules [38] for further formal analysis and calculation of feature model metrics.

The methodology is summarized in Fig. 3.

![Figure 3. Summary of methodology for feature model extraction](image)

3. Case study

For our case study, we have selected the Java Buffer library, which is a part of JDK 1.5 class library (package java.nio.*). The Java Buffer library is a benchmark source code component used by researchers [39, 40] in the area of program analysis, generalization and meta-programming research. The library contains 74 classes describing different buffers. Below, we briefly describe features of the Buffer classes and explain how those features are reflected in the Buffer classes (for a more detailed description, see [41]).

The class hierarchy of the Buffer library is organized in 3 levels. At Level 1 in the class hierarchy, there are seven classes that contain methods for providing access to buffer functionalities implemented in the classes at Level 2. At Level 2, classes implement two memory allocation schemes (direct, non-direct) and two byte orderings (native, non-native, Little Endian, Big Endian). Byte ordering matters for buffers, whose elements consist of multiple bytes. Twenty classes result from combining memory access and byte ordering features. Seven Heap classes implement the non-direct memory access scheme for a buffer. Classes with suffixes ‘U’ and ‘S’ implement direct memory access scheme with native and non-native byte ordering, respectively. At Level 3 in the class hierarchy, 25 classes implement different access modes of buffers. Summarizing, the Buffer library components have multiple features alongside many dimensions, their features depend upon each other, thus feature location and identification of feature locations is not an easy task. We formulate our aim as the identification of clusters of similar classes as composite features, and construction of a feature model consisting of composite and atomic features (we consider a stand-alone class or method as an atomic feature, though a class field may be an atomic feature, too).

Here as an example, we demonstrate the results of feature model extraction using 4 classes (DirectIntBufferRS, DirectIntBufferS, DirectIntBufferU, DirectIntBufferRU) from the Java Buffer library. The classes describe different direct buffers for storing integer type elements.

We use JDependencyFinder (http://depfind.sourceforge.net/) as a third-party tool to parse, analyze and extract dependencies from Java class files. The dependency graph is represented as a XML file. This file is used to construct the dissimilarity matrix automatically and saved using the Attribute-Relation File Format (ARFF) format. ARFF is a native format for WEKA (http://www.cs.waikato.ac.nz/ml/weka/), a suite of machine learning software written in Java, which we use for further analysis and clustering of features.

<table>
<thead>
<tr>
<th>Metric</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>No. of Inbound Intra-Class Method Dependencies</td>
<td>32</td>
</tr>
<tr>
<td>No. of Inbound Intra-Package Method Dependencies</td>
<td>4</td>
</tr>
<tr>
<td>No. of Outbound Intra-Class Feature Dependencies</td>
<td>104</td>
</tr>
<tr>
<td>No. of Outbound Intra-Package Feature Dependencies</td>
<td>58</td>
</tr>
<tr>
<td>No. of Outbound Intra-Package Class Dependencies</td>
<td>50</td>
</tr>
<tr>
<td>No. of Outbound Extra-Package Feature Dependencies</td>
<td>32</td>
</tr>
<tr>
<td>No. of Outbound Extra-Package Class Dependencies</td>
<td>37</td>
</tr>
</tbody>
</table>
The dependency graph of the analyzed classes contains two strongly connected components; therefore, the hierarchical structure of the graph is not trivial and can not be reduced to a uniquely defined perfect structure. The graph contains only one weakly connected component; therefore, features can not be separated easily. The complexity of the dependency graph extracted from these 4 classes is summarized in Table 1.

The features were clustered using the Cobweb algorithm and the obtained feature tree was converted into the feature model. The results of feature model extraction using the methodology described in subsection 2.5 are presented formally (textually) in Fig. 4 (as Prolog rules) and graphically in Fig. 5 (as a Feature Diagram).

![Figure 4. Prolog rules representing the extracted feature model](image)

![Figure 5. Graphical representation (feature diagram) of the extracted feature model of a subset of Buffer classes](image)

The relation of the features in the extracted feature model to the class methods are summarized in Table 2.

Analysing the results presented in Table 2, we can note that the proposed method has correctly identified and located composite features and separated them from other composite features representing buffer construction aspects (class constructors, duplication methods), predicate methods, functionality handling methods, and made a clear distinction between buffer classes with native (DirectIntBufferS) and non-native (DirectIntBufferU) byte ordering as well as read only buffer classes (DirectIntBufferRS, DirectIntBufferRU).

![Table 3. Metrics of a derived feature model](table)

Finally, in Table 3 we present some of the complexity metrics [42] of the derived executable feature model in Prolog (Fig. 4) computed automatically using the SWI-Prolog engine (http://www.swi-prolog.org/).

### 4. Conclusions and further work

In this paper, we have analysed the problem of reverse engineering source code to feature models. We presented a framework for the automated derivation of feature models from the existing Java programs, and proposed a method for feature model generation based on feature dependency extraction and clustering. The method is fully automatic and allows for generation of feature model descriptions in Feature Description Language (FDL) as well as Prolog rules, which can be further used for feature model validation, computation of product configuration and evaluation of feature model properties. The method could be used for: 1) partial configuration of software systems, when a
Table 2. Summary of composite features in Buffer feature model

<table>
<thead>
<tr>
<th>Composite feature</th>
<th>Constituent features</th>
<th>Class methods represented by atomic features</th>
<th>Description of composite feature</th>
</tr>
</thead>
<tbody>
<tr>
<td>n1</td>
<td>f7, f8</td>
<td>DirectIntBufferRS.isDirect, DirectIntBufferRS.isReadOnly</td>
<td>Info methods for direct read-only buffer class with non-native byte ordering</td>
</tr>
<tr>
<td>n2</td>
<td>f28, f29, f30, f31, f32, f33, f34, f35, f36, f37, f38, f39, f40, f41, f42, f43, f44</td>
<td>DirectIntBufferS.compact, DirectIntBufferS.get, DirectIntBufferS.put, DirectIntBufferS.address, DirectIntBufferS.slice, DirectIntBufferS.duplicate, DirectIntBufferS.getAddress, DirectIntBufferS.get, DirectIntBufferS.put, order, DirectIntBufferS.isDirect, DirectIntBufferS.isReadOnly, DirectIntBufferS.put, DirectIntBufferS.put, Order predicates for read-only buffer classes</td>
<td></td>
</tr>
<tr>
<td>n3</td>
<td>f2, n2</td>
<td>DirectIntBufferS.DirectIntBufferS, see n2</td>
<td>Buffer functionality handling methods for non-native byte ordering</td>
</tr>
<tr>
<td>n5</td>
<td>n6, n7</td>
<td>see n6, n7</td>
<td>Collection of predicate methods for read-only buffer classes</td>
</tr>
<tr>
<td>n6</td>
<td>f5, f9, f23, n9, n12</td>
<td>DirectIntBufferRS.asReadOnlyBuffer, DirectIntBufferRS.order, DirectIntBufferRU.order, see n9, n12</td>
<td>Order predicates for read-only buffer classes</td>
</tr>
<tr>
<td>n7</td>
<td>f21, f22</td>
<td>DirectIntBufferRU.isDirect, DirectIntBufferRU.isReadOnly</td>
<td>Info methods for direct read-only buffer class with native byte ordering</td>
</tr>
<tr>
<td>n8</td>
<td>f1, f3</td>
<td>DirectIntBufferRS.DirectIntBufferRS, DirectIntBufferRS.duplicate</td>
<td>Construction and duplication of read-only buffers with non-native byte ordering</td>
</tr>
<tr>
<td>n9</td>
<td>f0, f10, n8</td>
<td>DirectIntBufferRS.slice, DirectIntBufferU.DirectIntBufferU, see n8</td>
<td>Construction and duplication of buffers</td>
</tr>
<tr>
<td>n10</td>
<td>f15, f49, f50</td>
<td>DirectIntBufferRU.DirectIntBufferRU, DirectIntBufferU.slice, DirectIntBufferU.duplicate</td>
<td>Construction and duplication of buffers with native byte ordering</td>
</tr>
<tr>
<td>n11</td>
<td>f4, f6, f10, f11, f12, f13, f14, f15, f20, f24, f25, f26, f27</td>
<td>DirectIntBufferRS.asReadOnlyBuffer, DirectIntBufferRS.compact, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRU.compact, DirectIntBufferRU.put, DirectIntBufferRU.put, DirectIntBufferRU.put, DirectIntBufferRU.put</td>
<td>Buffer functionality handling methods for read-only buffers</td>
</tr>
<tr>
<td>n12</td>
<td>see n10, n11</td>
<td>DirectIntBufferRS.asReadOnlyBuffer, DirectIntBufferRS.compact, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRS.put, DirectIntBufferRU.compact, DirectIntBufferRU.put, DirectIntBufferRU.put, DirectIntBufferRU.put</td>
<td>Read-only buffers and buffers with native byte ordering</td>
</tr>
</tbody>
</table>

Future work will deal with the following problems:

1) **Performance.** The computational complexity of the proposed method is high (i.e., \(O(n^3)\) as determined by the Floyd’s algorithm). The performance must be improved, e.g., using approximate shortest path algorithms [43], to deal with large-scale real-world programs.

2) **Empirical research of alternative clustering algorithms.** Clustering is the critical part of the process of features location, because feature model has the same structure as clustering dendrogram. However, different clustering algorithms may produce different dendrograms on a graph of non-trivial complexity. This means that more than one clustering technique can be considered for comparative analysis and more complex case study organized to show and compare results of different clustering approaches with associated interpretations (descriptions of composite features) to internal nodes of computed dendrograms.

3) **Determination of feature model constraints.** Currently, only a subset of Feature Diagram notation is supported, which does not include the requires and excludes constraints. Feature models without...
constraints usually have a very large product space, which has to be reduced at a later modelling stage. Identification of constraints would greatly reduce the size of product space thus decreasing the need for further domain analysis. However, the extraction of constraints in a feature models will require additional analysis of source code and software dependencies.

4) Integration. The implementation of the method will be integrated into an existing feature modelling environment to allow for combining feature-based design methods with reverse engineering capabilities.

References


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